This document is the logbook for James Moran’s FMP. This logbook details key references to sources of information, key ideas drawn from these sources, technical and design information, discussions with my project supervisor (and any other parties involved in the project), preliminary thoughts and ideas, list of work to complete, along with plans, development of criteria for choices to be made, plus metrics for project tasks and results of technical proving exercises, experiments or technical/product evaluations.

James Moran

James Moran – FMP – Logbook

Contents

**No table of contents entries found.**

# Setting-Up a Plugin in Unreal Engine 4 (UE4)

To start off, I initiated the creation of a toolbar plugin, providing me with a base plugin, that I could build the Balanced FPS Level Generator on top of.

After attempting to have a sub-menu display to the user, via the button added to the top tool-bar of the editor, I decided it would make more sense to extend the editor’s menu listings (up to the top left corner of the default editor window).

For this, I followed a Live Training video, entitled ‘C++ Extending the Editor’, which has shown me how to add custom menu options, to the menu items list (for the ‘Edit’ sub-menu). (Noland, 2015)

This menu item will be added to the custom ‘Procedural’ category, on the ‘Edit’ sub-menu, as shown below (currently a blank box is shown, as there are no children of the UBaseEditorTool class, to be displayed in this category, from which, the Balanced FPS Level Generator will derive from):



This will then show an Edit Properties dialog for the user to choose constraints/other settings, before initiating the level generation (such as the area to generate a level in and bias of the generation for certain aspects of the level). An example of this is shown below:



Note the latest features you have added here!

# Considered Methods for Balancing the Space Filling Algorithm

First, looking at a paper, entitled ‘Procedural Generation of Balanced Levels for a 3D Paintball Game’. (Raul Lara-Cabrera et al, 2017)

In this paper, the idea of using zones, with edges between the zones (up to a certain threshold) will be utilised. A vector representation, holding three specific groups of values will be used for each zone. First, the coordinates of the zone, then the density of obstacles in that zone and finally, the density of obstacles for edges, are taken into consideration. (Raul Lara-Cabrera et al, 2017)

In order to maintain a balanced map (level), with no clear advantage for either team, coefficients for defensiveness, flanking and dispersion are used, along with the mean and standard deviation of the defensiveness and flanking values of the zones. (Raul Lara-Cabrera et al, 2017)

The defensiveness of a zone, is determined by the following factors:

* The density of the obstacles within that zone
* The density of the obstacles between that zone and the nearest zones (on the edges)

(Raul Lara-Cabrera et al, 2017)

Considerations for the flanking coefficient, are shown on the next page.

To alter how the level is generated, the generator will use a mutation-operator. The mutation operator applies pseudo-random permutations to the values of an individual vector (as noted in the 2nd paragraph of this section), adding to or multiplying by a respective pseudo-random value. The decision of adding or multiplying is also decided upon by chance, with the same probability. If an individual vector is mutated to such an extent, that it becomes invalid for the FPSLevelGenerator’s requirements, the algorithm will not consider this vector for the map. The map graph is then recalculated after this mutation, to include new edges between zones, if they become close enough because of it. (Raul Lara-Cabrera et al, 2017)

This ties in with Wang Tiles quite well, as a tile and its edges can represent a zone and its edges. A unit measurement for this project is one Unreal Unit (UU), which equates to 1 metre.

Using the Defensiveness, Flanking and Dispersion values, in an equation, to calculate an ‘Overall Compatibility’ value, comes out as follows:

(Raul Lara-Cabrera et al, 2017)

Where α, β and Γ are the coefficients for defensiveness, flanking and dispersion respectively. (µd µk) is the mean and (σd, σk) is the standard deviation, of the defensive and flanking values respectively. (Raul Lara-Cabrera et al, 2017)

For the defensiveness coefficient, the following equation is used:

(Raul Lara-Cabrera et al, 2017)

Where the density of obstacles within that zone (Densityi), is calculated with the following equation:

(Raul Lara-Cabrera et al, 2017)

With δi equating to the object density of zone i and δMAX equating to the highest density.

For the density of the paths to and from that zone, the following equation is used:

(Raul Lara-Cabrera et al, 2017)

Where γi is the density of objects in zone i and δj represents the density of objects in edge j.

For the flanking coefficient, this equation is used:

(Raul Lara-Cabrera et al, 2017)

Where φi is the number of connected zones in the sub graph, created from the adjacent zones to the node being considered, not including that zone itself and γi is the number of zones connected to the node being considered. If this zone has no connected zones, its flanking coefficient is zero (for example, a zone is in between 5 other zones, with the top 2 zones only being connected to each other and the centre zone, with the bottom 3 zones only being connected to each other and the centre zone. After taking the centre zone out of consideration, there are two sets of connected zones, so ki = 1 – 2/5 = 3/5). (Raul Lara-Cabrera et al, 2017)

For the edges, edge density is used to represent the colour of an edge. This is calculated from the volume taken up by objects in the zone (in UU3), divided by the mean distance (in UU) of these objects, from the centre point of the edge. These equations are used for such:

δj is then checked against the range of values used to determine the colour of an edge. Where if

The following diagram demonstrates the use of these equations:



(Paint Pixel-Based Calculations)

749: Height (80 UU), 551: Width (60 UU)

(308, 21): Centre Edge Point.

Distance ((462, 175), (308, 21)) =

Distance ((220, 379), (308, 21)) =

Distance ((214, 606), (308, 21)) =

Distance ((389, 606), (308, 21)) =

# Software Development Analysis of Classes for the Method Detailed In: ‘Procedural Generation of Balanced Levels for a 3D Paintball Game’

From this considered method for balancing the space filling algorithm, the following classes can be discerned from it:

* Area (with position coordinates, extents and area object density)
* Zone (inheriting from Area, including the zone’s edges)
* Edge (that of the connection point to and from zones, that are close enough to each other)

These can be represented in a Class Diagram (as shown below):

# Bibliography

**There are no sources in the current document.**

# References

CABRERA, R., L., *et al*, 2017. *Procedural Generation of Balanced Levels for a 3D Paintball Game*. Madrid: Universidad Autonoma de Madrid

NOLAND, M., 2015. C++ Extending the Editor | Live Training | Unreal Engine. [Viewed on the 04/03/2018]. Available from: <https://www.youtube.com/watch?v=zg_VstBxDi8&t=1364s>